MIMO Introduction

- MIMO are for a) diversity gain, and/or
 b) multiplexing gain
- 1. Create **diversity** for combating fading
 - With sufficient antenna spacing (10 wavelengths), each antenna experiences independent fading → When one signal is in its deep fade, others are unlikely the same
- 2. Increase throughput
 - Data stream is first S/P, each sub-sequence mapped to an antenna → This creates many "digital pipes" to support higher rate
- 3. When multiplexing gain is not used to increase throughput, it can support **multiple users**
 - With multiple receive antennas, each spatially separated user has a unique set of CIRs seen at receiver → This enables SDMA
- 4. Beamforming, antenna spacing half of wavelength
 - Improve signal quality or support SDMA

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MIMO/Beamforming

• MIMO classification: single-input single-output (SISO), single-input multi-output (SIMO), multi-input single-output (MISO), and **multi-input multi-output** (MIMO)



- Beamforming (transmit/receive) classification
 - **Digital** beamforming: baseband, one RF chain for each antenna, multi data streams/users
 - Analog beamforming: RF band, one RF chain for whole antenna array, one data stream
 - Hybrid beamforming, both base band/RF band, multi data streams/users



Fractional-Spaced Sampling

- Single-user (SISO) system with **fractional-space** sampling
 - At each symbol period take more than one sample \Rightarrow multiple (symbol-rate) subchannel models
 - Advantage: robust to carrier/timing recovery errors, perfect reconstruction with finite equalizer
 - **Disadvantage**: noise sample no longer white
- **Baseband** model with $T_s/2$ -spaced receiver:
 - Take two samples during each symbol period
 - $T_s/2$ -spaced equaliser: $\bar{y}(n) = \bar{\mathbf{w}}^H \bar{\mathbf{r}}(n)$ with $\bar{\mathbf{r}}(n) = [\bar{r}(n) \ \bar{r}(n-1) \cdots \bar{r}(n-2m+1)]^T$ and $\bar{\mathbf{w}} = [\bar{w}_0 \ \bar{w}_1 \cdots \bar{w}_{2m-1}]^T$
 - $\bar{y}(n)$ is decimated by a factor of 2 to get T_s -spaced output y(k)



• Multirate model with $T_s/2$ -spaced equaliser

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- k indicates T_s -spaced quantities and n indicates $T_s/2$ -spaced quantities





Multirate/Multichannel Model

• $T_s/2$ -spaced sequence $\{\bar{s}(n)\}$ is zero-filled transmitted symbol sequence $\{s(k)\}$ defined by

$$ar{s}(n) = \left\{ egin{array}{cc} s(n/2), & \mbox{ for even } n \ 0, & \mbox{ for odd } n \end{array}
ight.$$

• Received $T_s/2$ -spaced signal sample is

$$\bar{r}(n) = \sum_{i=0}^{2N_c - 1} \bar{a}_i \bar{s}(n - i) + \bar{e}(n)$$

• $T_s/2$ -spaced complex-valued channel impulse response (CIR) is given by

$$\bar{\mathbf{a}} = \left[\bar{a}_0 \ \bar{a}_1 \ \bar{a}_2 \ \bar{a}_3 \cdots \bar{a}_{2N_c-1}\right]^T$$

- Sampling at twice of symbol rate ⇒ Two symbol-spaced models: Odd sample model and even sample model, i.e., multichannel model
- Take even and odd samples of noise and Rx signal

$$e^{e}(k) = \bar{e}(2n), \ e^{o}(k) = \bar{e}(2n+1), \ r^{e}(k) = \bar{r}(2n), \ r^{o}(k) = \bar{r}(2n+1)$$

• Define even and odd channels and equalisers (all are symbol-rate sequences) as:

$$\bar{\mathbf{a}}^{e} = [\bar{a}_{0} \ \bar{a}_{2} \cdots \bar{a}_{2N_{c}-2}]^{T}, \ \bar{\mathbf{a}}^{o} = [\bar{a}_{1} \ \bar{a}_{3} \cdots \bar{a}_{2N_{c}-1}]^{T}, \bar{\mathbf{w}}^{e} = [\bar{w}_{0} \ \bar{w}_{2} \cdots \bar{w}_{2m-2}]^{T}, \ \bar{\mathbf{w}}^{o} = [\bar{w}_{1} \ \bar{w}_{3} \cdots \bar{w}_{2m-1}]^{T}$$



• Symbol-rate output

$$y(k) = \sum_{i=0}^{2m-1} w_i^* r(k-i) = \mathbf{w}^H \mathbf{r}(k)$$

with
$$\mathbf{w} = \begin{bmatrix} (\bar{\mathbf{w}}^{\mathrm{o}})^T & (\bar{\mathbf{w}}^{\mathrm{e}})^T \end{bmatrix}^T$$
 and
 $\mathbf{r}(k) = \begin{bmatrix} (\mathbf{r}^{\mathrm{e}}(k))^T & (\mathbf{r}^{\mathrm{o}}(k))^T \end{bmatrix}^T$



- In general, T_s/K -spaced sampling will result in K channel models
- As we have symbol-rate model $y(k) = \mathbf{w}^H \mathbf{r}(k)$, all equalisation results apply
- Blind equalisation example: consists of a 22-tap $T_s/2$ channel and a 26-tap $T_s/2$ equaliser with 256-QAM and SNR= 60 dB
- In simulation, an estimated MSE based on a separate block of data and the maximum distortion measure defined by $\sum_{n \in I} n_{tot} + f = -1$

$$\mathrm{MD} = \frac{\sum_{i=0}^{n_{\mathrm{tot}}} |f_i| - |f_{i_{\mathrm{max}}}|}{|f_{i_{\mathrm{max}}}|}$$

are used to assess convergence rate, where

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$$\mathbf{f} = \left[f_0 \ f_1 \cdots f_{n_{\text{tot}}}\right]^T = \left(\bar{\mathbf{w}}^{\text{o}}\right)^* \star \bar{\mathbf{a}}^{\text{e}} + \left(\bar{\mathbf{w}}^{\text{e}}\right)^* \star \bar{\mathbf{a}}^{\text{o}}$$

is the combined impulse response of the channel and equaliser, $f_{i_{\max}} = \max\{f_i, \ 0 \le i \le n_{\mathrm{tot}}\}$





Simulation Results



Digital Beamforming Assisted Receiver

- MIMO based SDMA system:
 - Uplink, BS digital beamforming receiver to implement **multiuser detection**
 - Assume L receiver antennas supporting K single-antenna users
 - Narrowband channels with $m_i(k)$ = $A_i b_i(k)$, A_i : channel coefficient for user i and $b_i(k)$: kth symbol of user i
 - Symbol-rate sampling, BS detects user idata for $1 \leq i \leq K$
- Uniformly spaced linear antenna array:
 - $-t_l(\theta_i)$ be relative time delay at array element l for user i
 - θ_i angle of arrival for user i and carrier $\omega = 2\pi f_c$

i=1



user $1 \rightarrow modulator$

modulator

user 21





 $n_1(t)$

 $n_2(t)$

 $n_{I}(t)$

 $\Sigma \rightarrow X_1(t)$

Receiver

Beamforming Assisted Receiver (continue)

• System model: Antenna array output $\mathbf{x}(k) = [x_1(k) \ x_2(k) \cdots x_L(k)]^T$ is expressed as

$$\mathbf{x}(k) = \bar{\mathbf{x}}(k) + \mathbf{n}(k) = \mathbf{H}\mathbf{b}(k) + \mathbf{n}(k)$$

where $\mathbf{n}(k) = [n_1(k) \ n_2(k) \cdots n_L(k)]^T$ has a covariance matrix of $E[\mathbf{n}(k)\mathbf{n}^H(k)] = 2\sigma_n^2 \mathbf{I}_L$ with \mathbf{I}_L representing the $L \times L$ identity matrix, uplink channel matrix \mathbf{H} is given by

$$\mathbf{H} = [\mathbf{h}_1 \ \mathbf{h}_2 \cdots \mathbf{h}_K] = [A_1 \mathbf{s}_1 \ A_2 \mathbf{s}_2 \cdots A_K \mathbf{s}_K]$$

steering vector for source \boldsymbol{i} is

$$\mathbf{s}_i = \left[\exp(j\omega t_1(heta_i)) \ \exp(j\omega t_2(heta_i)) \cdots \exp(j\omega t_L(heta_i))
ight]^T$$

and transmitted symbol vector $\mathbf{b}(k) = [b_1(k) \ b_2(k) \cdots b_K(k)]^T$

• Given channel matrix H, maximum likelihood MUD

$$\widehat{\mathbf{b}}_{\mathrm{ML}}(k) = rg\min_{\mathbf{b}\in\mathcal{B}} \|\mathbf{x}(k) - \mathbf{Hb}\|$$

Feasible solution set $\mathcal{B} = \{\mathbf{b}_1, \cdots, \mathbf{b}_{N_f}\}$, with $N_f = K^M$ for M-QAM

• Linear beanforming/MUD: BS beamformer output vector $\mathbf{y}(k) = [y_1(k) \cdots y_K(k)]^T$

$$\widehat{\mathbf{b}}(k) = \mathbf{y}(k) = \mathbf{W}^H \mathbf{x}(k)$$

Beamformer complex-valued weight matrix $\mathbf{W} = [\mathbf{w}_1 \cdots \mathbf{w}_K]$ with $\mathbf{w}_i = [w_{1,i} \cdots w_{L,i}]^T$

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Linear Beamforming/MUD

• Zero-forcing (ZF) beamforming/MUD

$$\mathbf{W}_{\mathrm{ZF}}^{H} = \left(\mathbf{H}^{H}\mathbf{H}\right)^{-1}\mathbf{H}^{H} \text{ or } \mathbf{W}_{\mathrm{ZF}} = \mathbf{H}\left(\mathbf{H}^{H}\mathbf{H}\right)^{-1}$$

• Minimum mean square error (MMSE) beamforming/MUD

$$\mathbf{W}_{\mathrm{MMSE}}^{H} = \left(\mathbf{H}^{H}\mathbf{H} + \frac{2\sigma_{n}^{2}}{\sigma_{s}^{2}}\mathbf{I}_{K}\right)^{-1}\mathbf{H}^{H} \text{ or } \mathbf{W}_{\mathrm{MMSE}} = \mathbf{H}\left(\mathbf{H}^{H}\mathbf{H} + \frac{2\sigma_{n}^{2}}{\sigma_{s}^{2}}\mathbf{I}_{K}\right)^{-1}$$

with $E[|b_i(k)|^2] = \sigma_s^2$. For user i,

$$\mathbf{w}_{i,\text{MMSE}} = \left(\mathbf{H}\mathbf{H}^{H} + \frac{2\sigma_{n}^{2}}{\sigma_{s}^{2}}\mathbf{I}_{L}\right)^{-1}\mathbf{h}_{i}$$

MMSE solution can be implemented adaptively using the LMS or RLS algorithm

• Further consider for user *i*, beamformer's output is given by

$$y_i(k) = \mathbf{w}_i^H \mathbf{x}(k) = \mathbf{w}_i^H \bar{\mathbf{x}}(k) + \mathbf{w}_i^H \mathbf{n}(k) = \bar{y}_i(k) + e_i(k)$$

where $e_i(k)$ is Gaussian distributed having a zero mean and $E[|e_i(k)|^2] = 2\sigma_n^2 \mathbf{w}_i^H \mathbf{w}_i$

• Assume M-QAM modulation and define combined impulse response of beamformer and system as

$$\mathbf{w}_i^H \mathbf{H} = \mathbf{w}_i^H [\mathbf{h}_1 \ \mathbf{h}_2 \cdots \mathbf{h}_K] = [c_{i,1} \ c_{i,2} \cdots c_{i,K}]$$



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Linear Beamforming/MUD (continue)

• Minimum symbol error rate: beamformer's output can also be expressed as

$$y_i(k) = c_{i,i}b_i(k) + \sum_{1 \le l \le K, l \ne i} c_{i,l}b_l(k) + e_i(k)$$

• Define decision variable as $d_i(k) = d_{i_R}(k) + jd_{i_I}(k) = \frac{y_i(k)}{c_{i,i}}$, then symbol decision $\hat{b}_i(k) = \hat{b}_{i_R}(k) + j\hat{b}_{i_I}(k)$ is given by

$$\widehat{b}_{i_R}(k) = \begin{cases} u_1, & \text{if } d_{i_R}(k) \leq u_1 + 1 \\ u_l, & \text{if } u_l - 1 < d_{i_R}(k) \leq u_l + 1 \text{ for } 2 \leq l \leq \sqrt{M} - 1 \\ u_{\sqrt{M}}, & \text{if } d_{i_R}(k) > u_{\sqrt{M}} - 1 \end{cases}$$

$$\widehat{b}_{i_{I}}(k) = \begin{cases} u_{1}, & \text{if } d_{i_{I}}(k) \leq u_{1} + 1 \\ u_{q}, & \text{if } u_{q} - 1 < d_{i_{I}}(k) \leq u_{q} + 1 \text{ for } 2 \leq q \leq \sqrt{M} - 1 \\ u_{\sqrt{M}}, & \text{if } d_{i_{I}}(k) > u_{\sqrt{M}} - 1 \end{cases}$$

where *M*-QAM symbol set is defined as $\{u_l + ju_q, 1 \leq l, q \leq \sqrt{M}\}$

- Given H, we have set of \bar{y}_i , which is function of w_i , and symbol error rate is **mixture** of Q functions
- Minimize this symbol error rate leads to MSER solution $\mathbf{w}_{i\mathrm{MSER}}$

Adaptive MBER Beamforming Solution

- We can derive minimum symbol error rate solution $\mathbf{w}_{i,\mathrm{MSER}}$ for general QAM
 - Unlike MMSE solution, there is no closed-form solution for $\mathbf{w}_{i,\mathrm{MSER}}$
 - Gradient optimisation must be used
- MSER solution can be implemented adaptively using the LSER algorithm
- For details see:

S. Chen, H.-Q. Du and L. Hanzo, "Adaptive minimum symbol error rate beamforming assisted receiver for quadrature amplitude modulation systems," in *VTC2006-Spring* (Melbourne, Australia), May 7-10, 2006

PDF copy can be download from: https://www.southampton.ac.uk/~sqc/ELEC6214/

• Example: 16QAM, 4 users, 3-element antenna array

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Transmit Beamforming/Precoding

• BS employs N transmit antennas to communicate with K single-receive-antenna MSs, i.e. downlink



- MSs unable to perform multiuser detection or receive beamforming
 - BS does multiuser transmission/transmit beamforming/precoding to combat MUI
- Received signal vector of K MSs, $\mathbf{y}(k) = [y_1(k) \ y_2(k) \cdots y_K(k)]^T$, is given by

$$\mathbf{y}(k) = \mathbf{H}^T \mathbf{P} \mathbf{x}(k) + \alpha^{-1} \mathbf{n}(k)$$

- Transmit vector $\mathbf{x}(k) = [x_1(k) \ x_2(k) \cdots x_K(k)]^T$
- Downlink channel matrix $\mathbf{H} = [\mathbf{h}_1 \ \mathbf{h}_2 \cdots \mathbf{h}_K] \in \mathbb{C}^{N \times K}$
- Precoding matrix $\mathbf{P} = [\mathbf{p}_1 \ \mathbf{p}_2 \cdots \mathbf{p}_K] \in \mathbb{C}^{N \times K}$

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– $\mathbf{n}(k)$ is AWGN vector, and α a transmit power normalization factor

Digital Precoding Design

- $\bullet\,$ The task is to design the precoding matrix ${\bf P}$ so that
 - *i*th MS's receive signal $y_i(k)$ is **sufficient** statistic to detect $x_i(k)$
 - Zero-forcing precoding: $\mathbf{P}_{\mathrm{ZF}} = \mathbf{H}^* \big(\mathbf{H}^T \mathbf{H}^* \big)^{-1}$
 - Similarly one can have MMSE precoding, and even MBER precoding
- BS cannot estimate downlink channel matrix, and MSs have to feed back corresponding downlink channel estimates to BS
- For TDD, uplink channel and downlink channel are reciprocal
 - BS can estimate uplink channel, which is needed in uplink MUD, and it can use estimated uplink channel as downlink channel in precoding design
- Fundamentally, for TDD, uplink receive beamforming or MUD is exactly equivalent to downlink transmit beamforming or MUT
- 1. L.-L. Yang, "Design of linear multiuser transmitters from linear multiuser receivers," in *Proc. ICC* 2007 (Glasgow, Scotland), June 24-28, 2007, pp. 5258–5263
- S. Chen and L.-L. Yang, "Downlink MBER beamforming design based on uplink MBER receive beamforming for TDD-SDMA induced MIMO systems," *Communications and Networks*, vol.2, pp. 145–151, Aug. 2010



Summary

- MIMO system introduction: diversity gain and multiplexing gain
- Single-user fractional-spaced receiver

Baseband continuous-time model, discrete-time multirate model, discrete-time multichannel model

- Digital beamforming assisted receiver for QAM modulation
 - Also known as multiuser detection
- Digital transmit beamforming or precoding
 - Also known as multiuser transmission
- For TDD, equivalency of uplink receive beamforming or MUD and downlink transmit beamforming or MUT

