

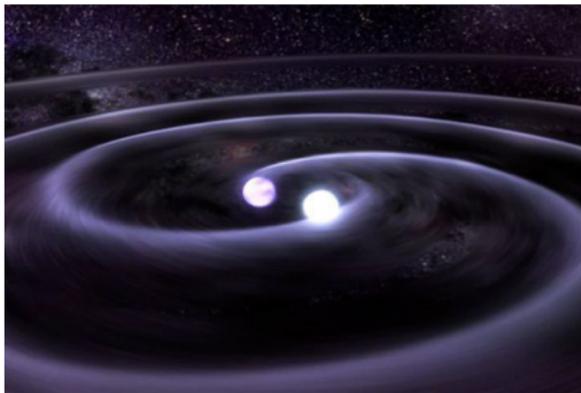
Extended-body effects in general relativity

What is possible?

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Dublin City University

Southampton Gravity Seminar
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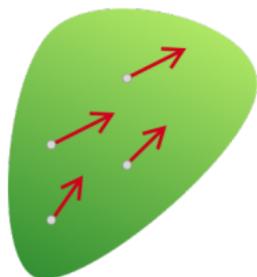
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Equivalence principle: Free-fall is universal

Is that *really* how things fall?

In Newtonian gravity,

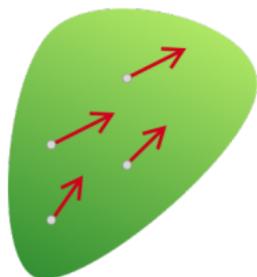
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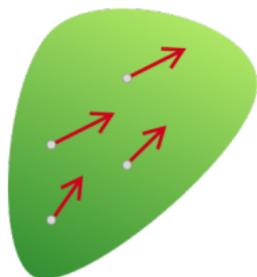


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When is this *exactly* equal to $-\nabla\phi$?
... at least when bodies are **spherical**.

$$\ddot{z}_i = -\nabla_i \phi + (?)$$

Two types of corrections:

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- 1 **Self-interaction** requires that ϕ be replaced by ϕ_{ext} .

$$\ddot{z}_i = \underbrace{-\nabla_i \phi_{\text{ext}}}_{\text{monopole}} - \frac{1}{2} \overbrace{\left(Q^{jk} / m \right)}^{(\text{quadrupole moment})} \nabla_i \nabla_j \nabla_k \phi_{\text{ext}} + \dots$$

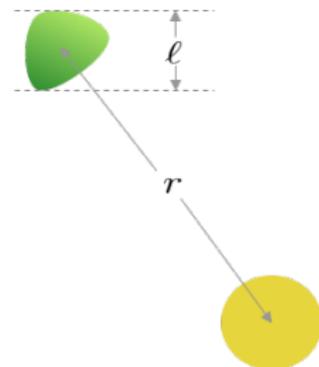
quadrupole

Two types of corrections:

- 1 Self-interaction requires that ϕ be replaced by ϕ_{ext} .
- 2 Extended-body effects bring in aspects of the internal structure: Free-fall is no longer universal.

Newtonian extended-body effects

$$\ddot{z}_i = -\nabla_i \phi_{\text{ext}} - \underbrace{\frac{1}{2} (Q^{jk}/m) \nabla_i \nabla_j \nabla_k \phi_{\text{ext}}}_{\mathcal{O}[(\ell/r)^2 \times (\text{monopole})]} + \dots$$



At leading nontrivial order, effects of internal structure are determined by the **quadrupole moment** $Q^{ij} \sim m\ell^2$.

Rocket-free maneuvering?

That which is not forbidden is allowed. . .

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. . . and maneuvers are forbidden mainly by symmetries.

- ① **Homogeneous gravitational field:** 6 symmetries fix 6 force and torque components \Rightarrow no maneuvering possible

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You need *gradients* to “grab onto...”

Extended-body effects derived in full by Dixon (1974), at least without self-interaction. Self-interaction incorporated later AIH (2012, 2015).

$$\begin{aligned}\dot{p}_a &= -\frac{1}{2}R_{abcd}\dot{z}^b S^{cd} + (\text{int struct}), \\ \dot{S}_{ab} &= 2p_{[a}\dot{z}_{b]} + (\text{int struct}).\end{aligned}$$

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There can also be a nontrivial momentum-velocity relation:

$$p^a = m\dot{z}^a + (\text{hidden momentum})$$

Universality of free-fall in GR

There are spin effects, but these aren't controllable.

First non-universal contributions to motion are from the **quadrupole moment**. This has 10 components in vacuum spacetimes.

Irrelevant quadrupole components

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② Type N:

- At least 6 components are irrelevant.
- For *linearly-polarized plane waves*, 9 are irrelevant.

③ ...

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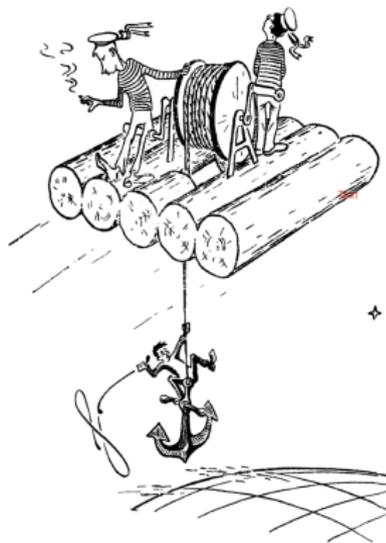
5 quadrupole components are irrelevant. 4 must be controlled to control the torque. There is **1 left over**. . . What can this do?

Everything is in the mass

Extended-body effects enter *only* via **changes in mass**:

$$dm = - \mathcal{J} d(M/r^3).$$

E and \vec{J} are conserved. E/m and \vec{J}/m are not.



[Beletsky, 2001]

Net mass changes

$$dm = - \mathcal{I} d(M/r^3),$$

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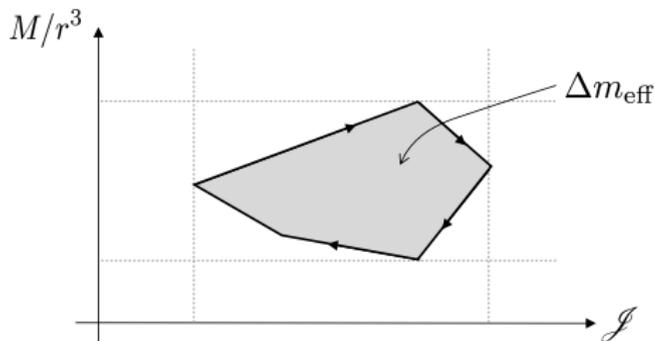
$$dm = - \mathcal{J} d(M/r^3), \quad d\left(\overbrace{m + \mathcal{J} M/r^3}^{m_{\text{eff}}}\right) = (M/r^3) d\mathcal{J}$$

" $-U_{\text{quad}}$ "

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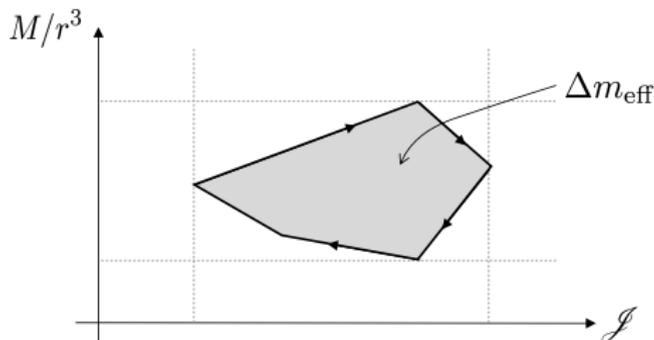
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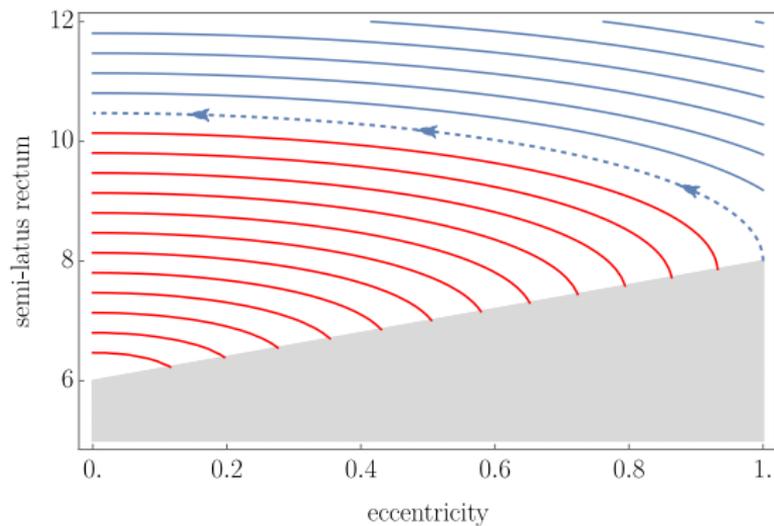
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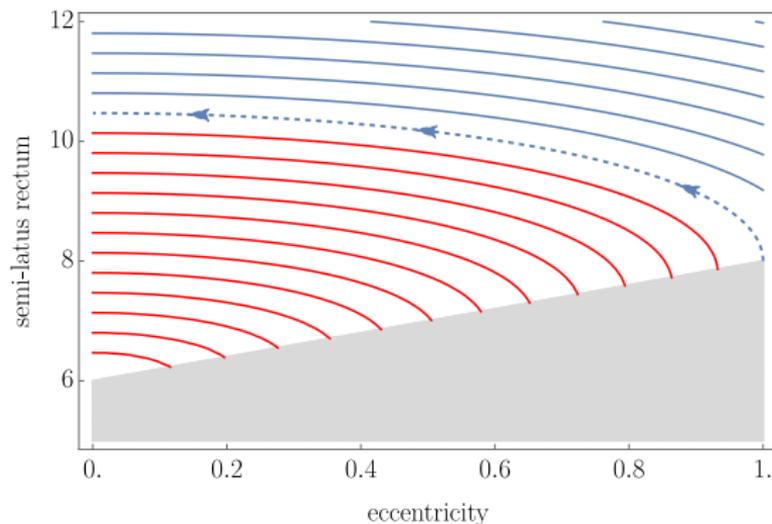


Repeating cycles with **nonzero area** raises or lowers the mass.

What do mass changes accomplish?

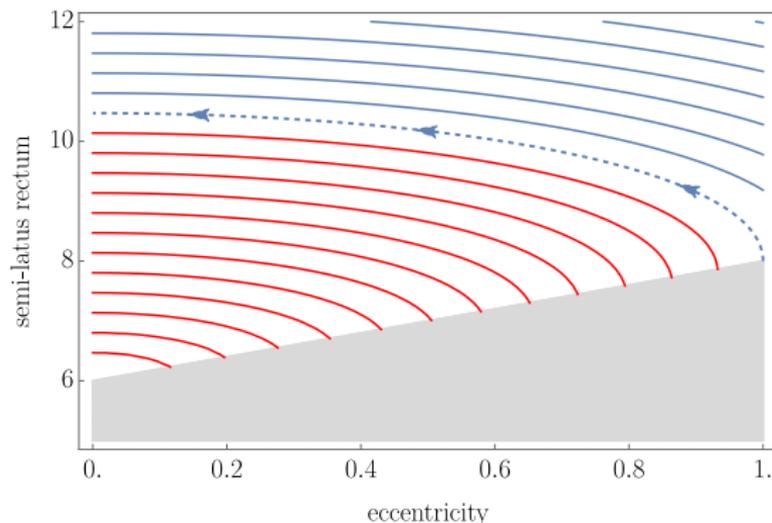


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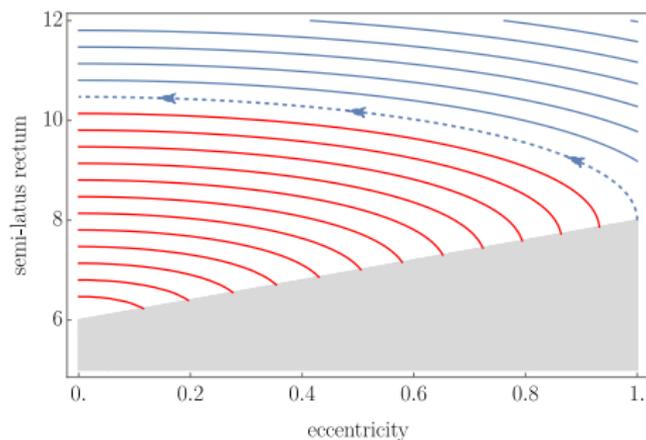
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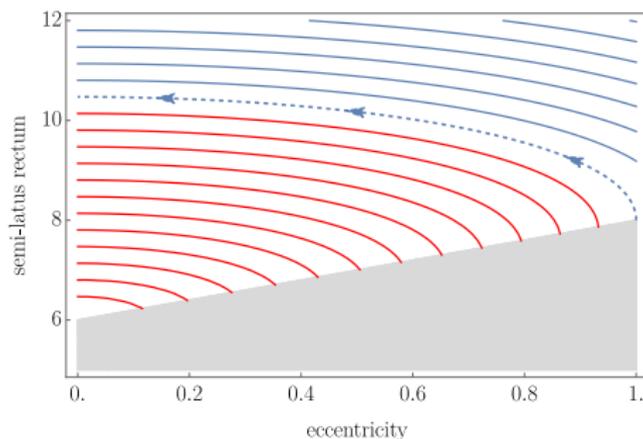
- Increasing mass \Rightarrow circularization
- Decreasing mass is more complicated...

Effect of decreasing mass



- 1 If $r_i > 2(3 + \sqrt{5})M \approx 10.5M$, you can escape!

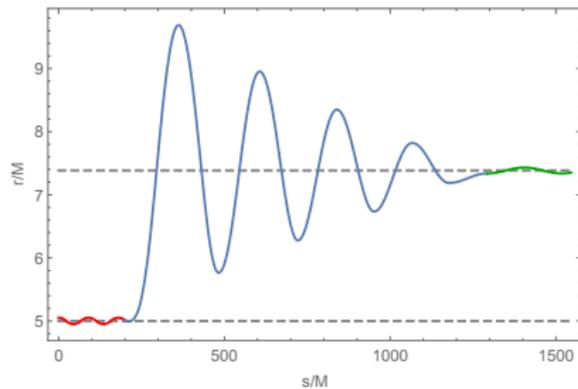
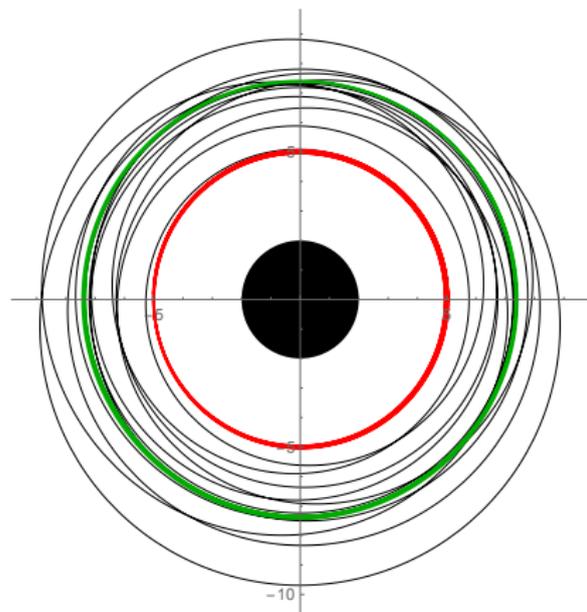
Effect of decreasing mass



- 1 If $r_i > 2(3 + \sqrt{5})M \approx 10.5M$, you can escape!
- 2 Otherwise, decreasing mass results in an approach to an unstable circular orbit, or a plunge.

Circular transfers

Move between pairs of circular geodesics with $4 < r/M < 10.5$.



Relativistic vs. Newtonian effects

[AIH (2020) vs. AIH & Gaffney (2020)]

In the spin-free, torque-free context, they're almost identical:

Concept	Relativistic	Newtonian
Torque-free force	$\nabla(\mathcal{J} M/r^3)$	$\nabla(\mathcal{J} M/r^3)$
Always constant	E, \vec{L}	m_N, \vec{L}
Const when \mathcal{J} jumps	m	E_{pt}
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$$E - m \sim E_{\text{pt}}, \quad E - m_{\text{eff}} \sim E_{\text{pt}} + U_{\text{ext}}$$

- 1 Extended-body effects allow objects to control their motion.
- 2 They can change mass, allowing for bound orbits to be unbound, for unstable orbits to be stabilized, and more.

Even more is possible with spin and torque. . . There are many options for those who wait!