

# Neural-network based optimisation of compliant mooring systems



**Oscar Festa**, PhD student from the University of Southampton

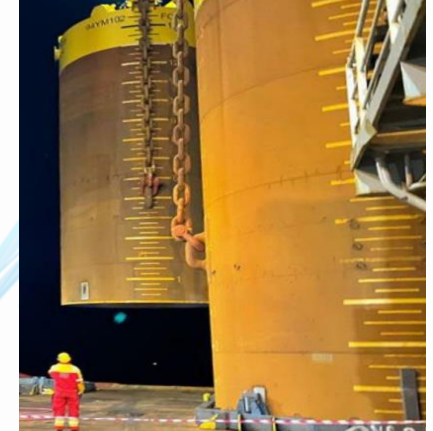
**Professor Susan Gourvenec**, RAEng Chair in Emerging Technologies for Intelligent & Resilient Ocean Engineering (IROE), University of Southampton

**Professor Adam Sobey**, Data-centric Engineering lead, The Alan Turing Institute

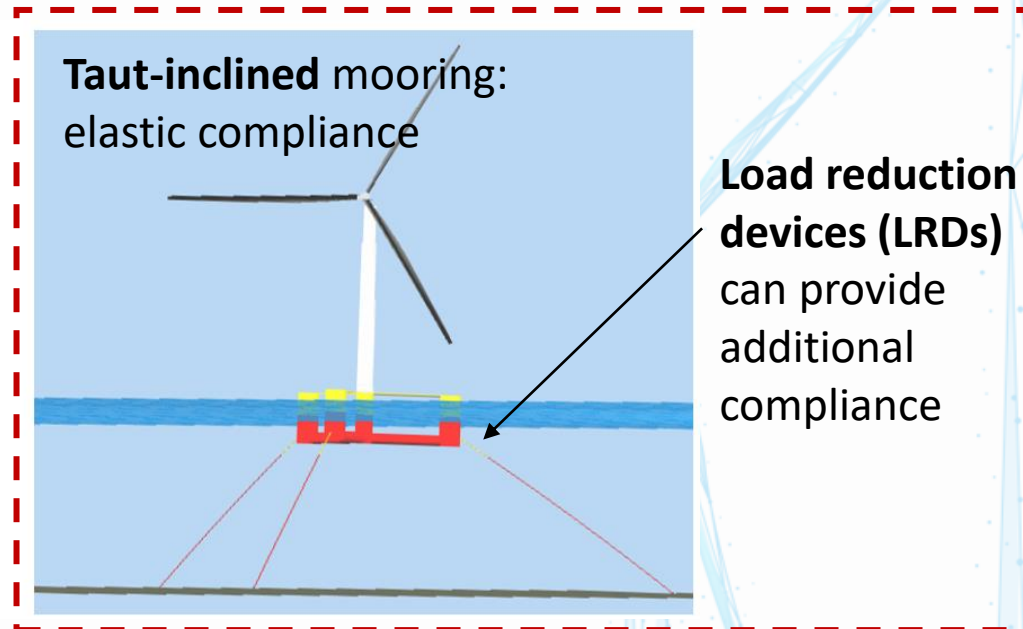
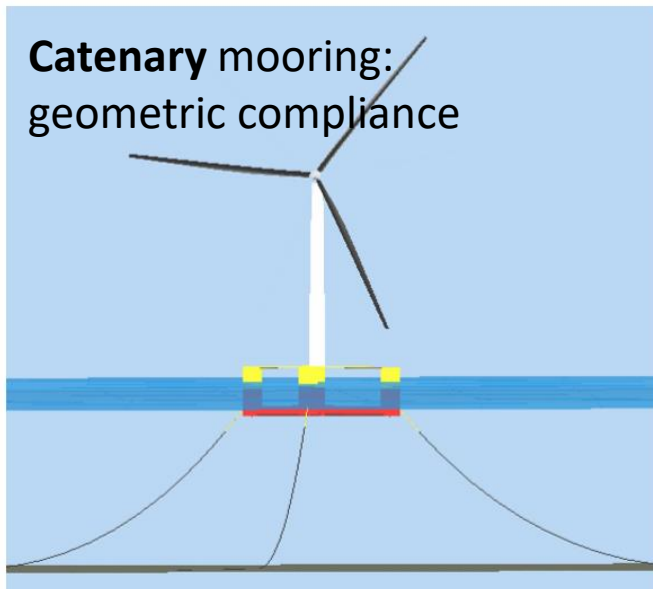
- FOWT mooring systems hold **high cost reduction potential**
- Mooring system design involves striking a balance between **stiffness** and **compliance**
- Cheaper, safer designs could be achieved by **optimising mooring system compliance**



161 mm mooring chain  
([Maritime executive](#))



Hywind Tampen anchors ([SEMAR](#))



*Can we use machine learning to optimise a taut mooring with LRDs?*

LRDs provide **targeted compliance**, offering high levels of extension without compromising breaking strength.

*LRD technology*

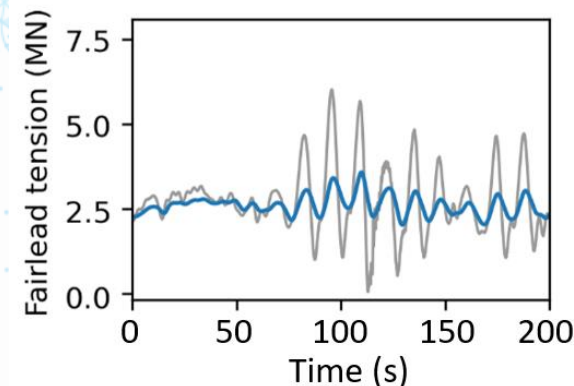
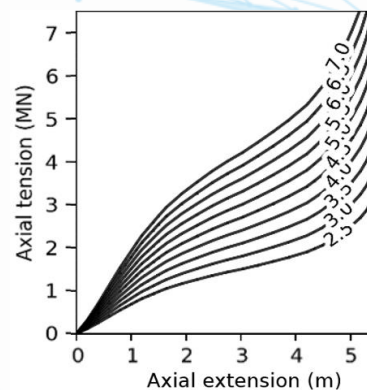
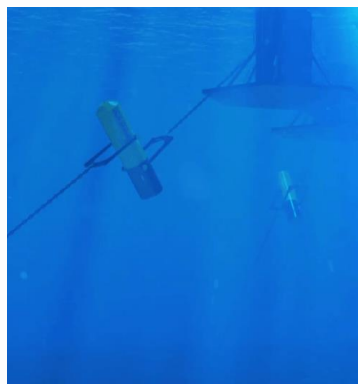
*Mechanism*

*Typical non-linear stiffness curves*

*Load reduction vs. conventional mooring*

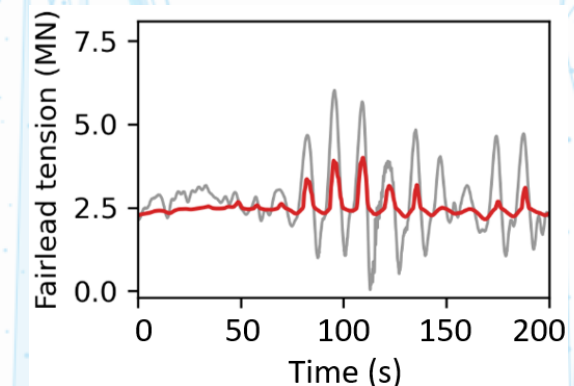
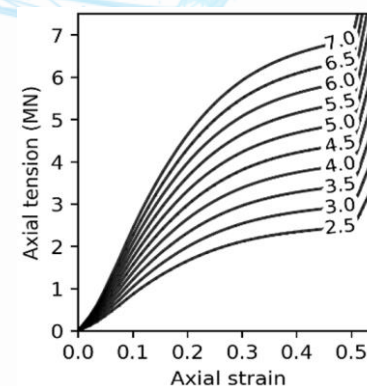
**Dublin Offshore LRD**

[www.dublinoffshore.ie/technology](http://www.dublinoffshore.ie/technology)

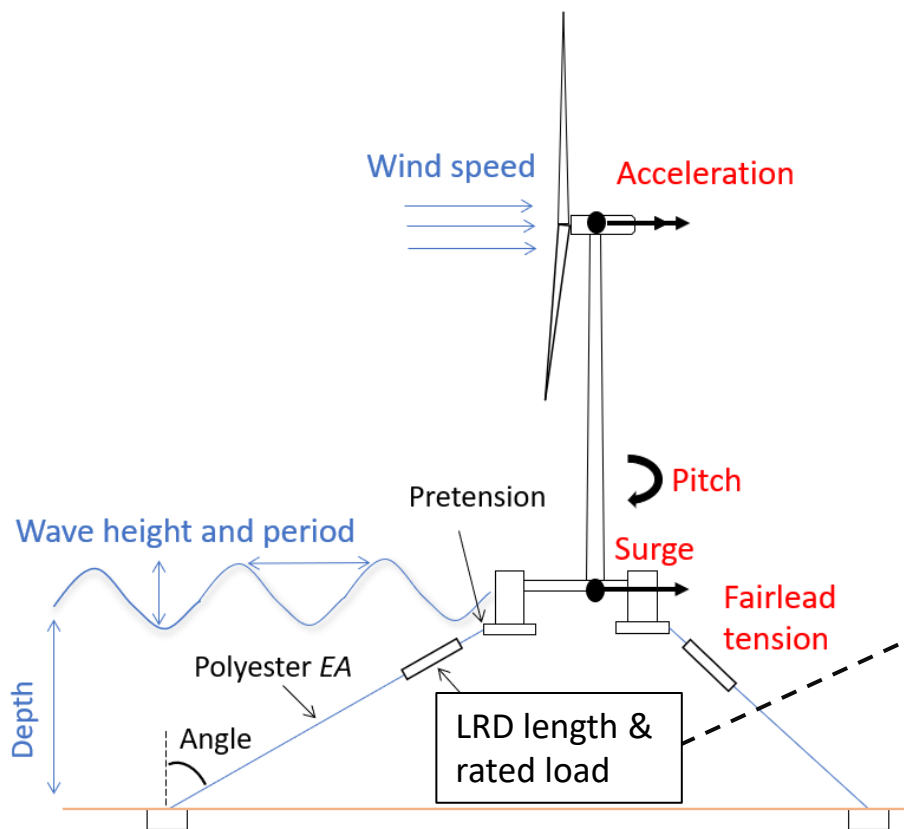


**TFI Seaspring**

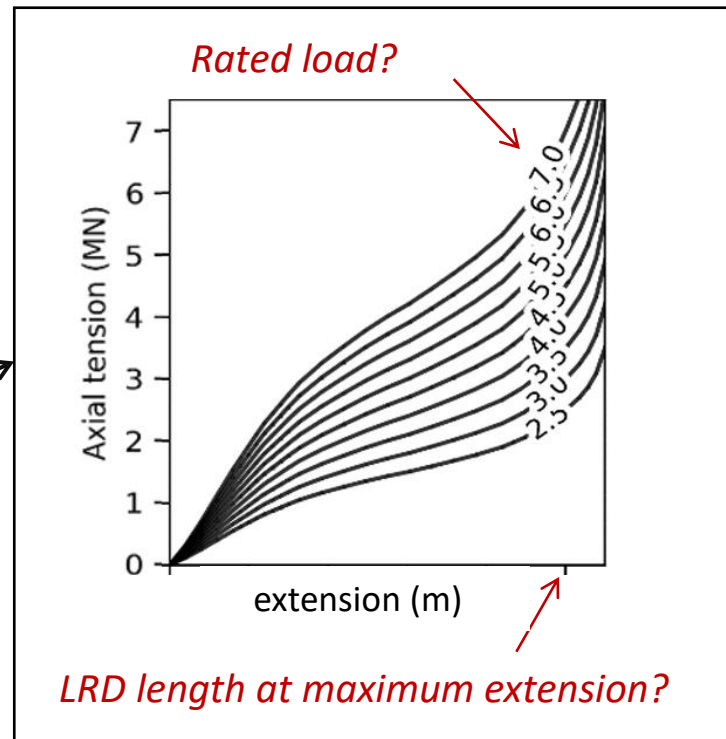
[www.tfimarine.com](http://www.tfimarine.com)



**Aim: Holistic and generalisable** optimisation of taut compliant mooring systems including LRDs

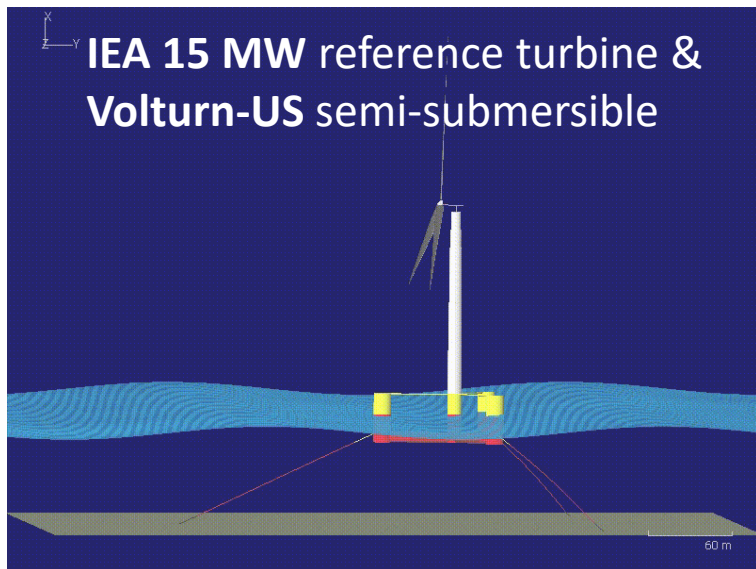


Location-specific parameters, mooring system & LRD parameters, **outputs**



## Model set-up:

- Fully-coupled aero-hydro-servo dynamic modelling, with commercial software **Flexcom**
- LRDs modelled as non-linear spring elements, with stiffness curves representative of TFI or Dublin Offshore devices



## Model parameter ranges:

### Mooring & LRD parameters

Mooring & LRD parameters	Design space
Mooring arrangement	Polyester taut
Pre-tension (kN)	500 - 2500
Polyester stiffness $EA$ (MN)	30 - 120
Line angle to vertical (deg)	55 - 80
LRD rated load (MN)	2 - 7
LRD spring element length (m)	10 - 30
LRD curve types	Dublin Offshore, TFI
Water depth (m)	60-150

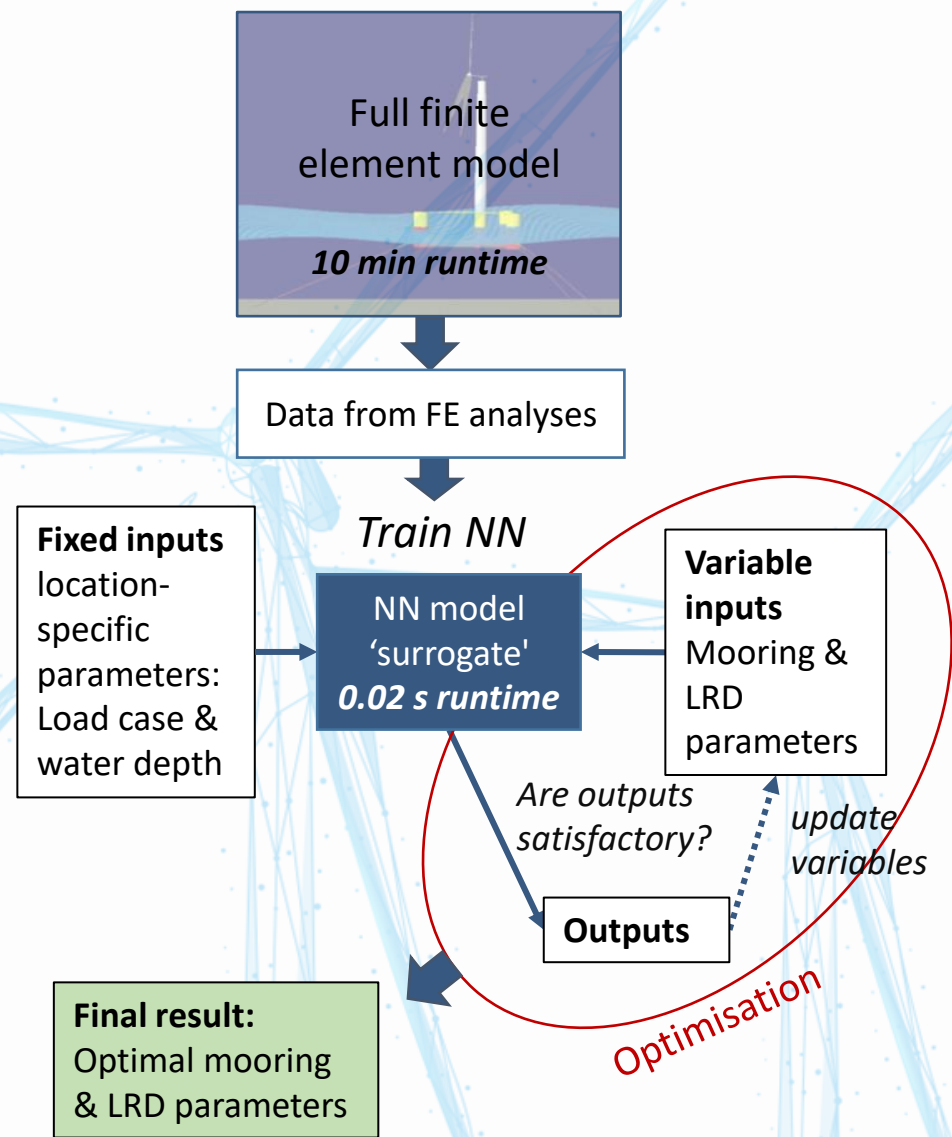
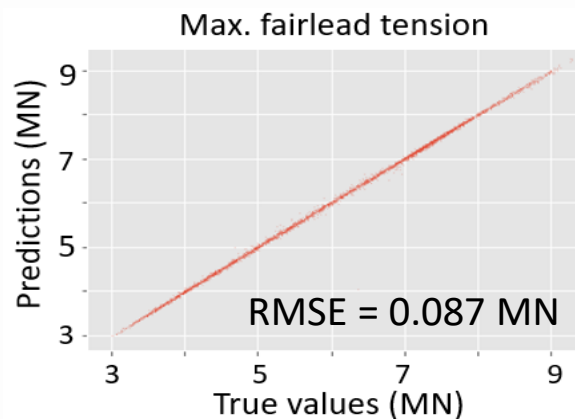
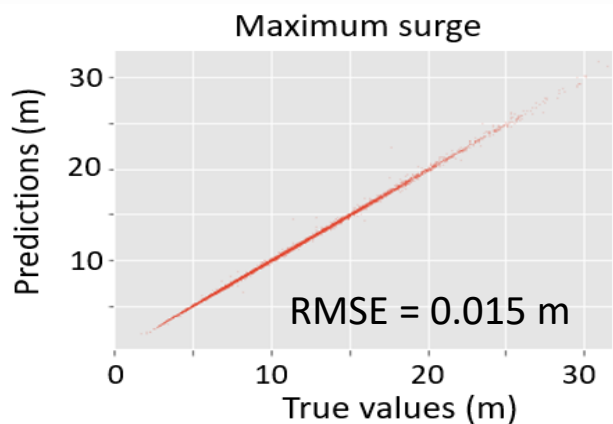
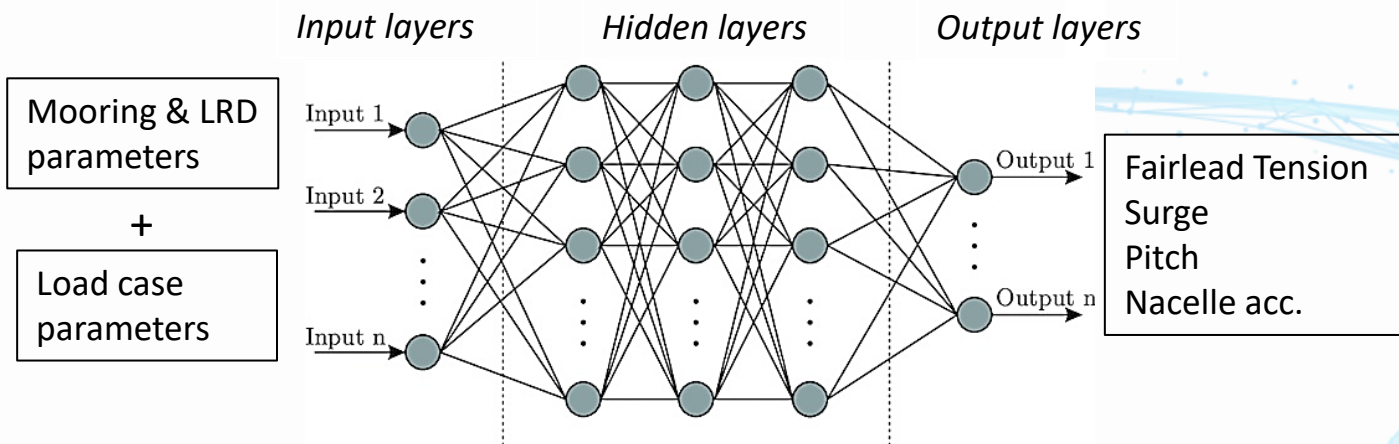
### Load case parameters

Load case parameters	Parked	Operating
Hub wind speed (m/s)	25 - 50	10.59 (rated)
Wave height (m)	10 - 25	2 - 15
Wave period (s)	8 - 18	6 - 16
Wind & wave direction (deg)	0	0
Current (m/s)	$0.015 U_{hub}$	$0.015 U_{hub}$



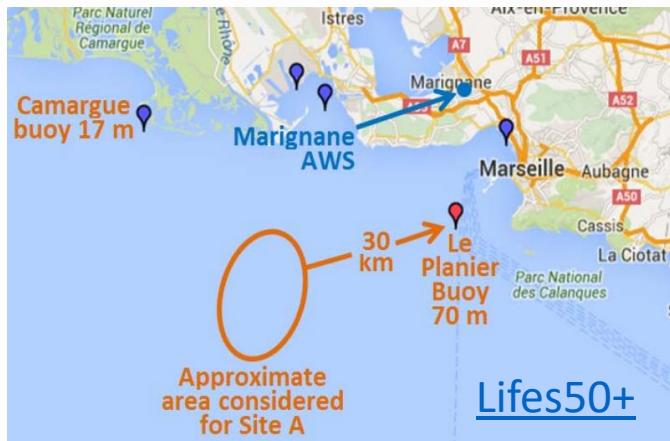
# Method (2/2) – Neural network

Surrogate neural network trained from 50k dynamic analyses provides an **instantaneous input – output relationship**

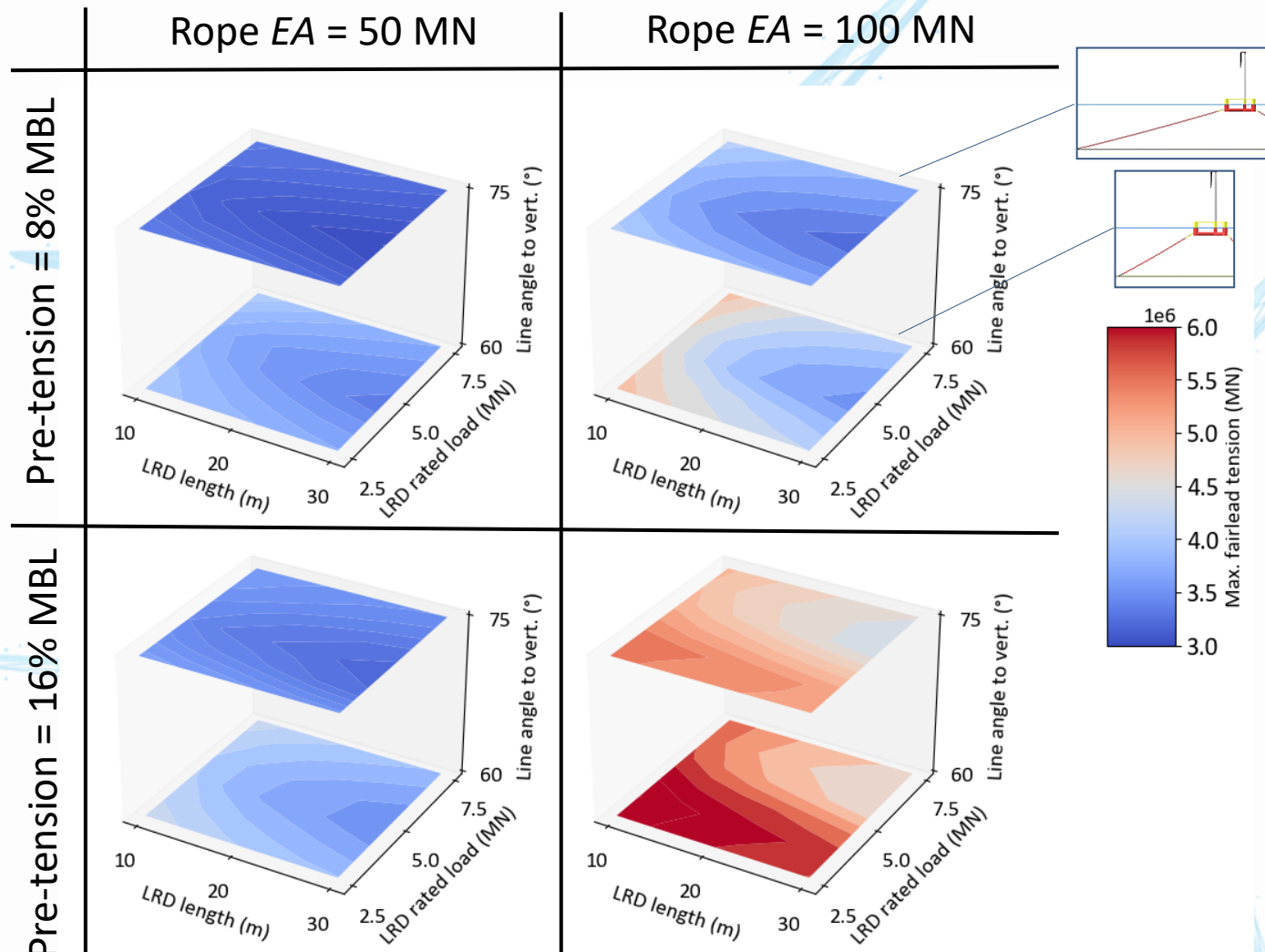


### Location A: Golfe de Fos

Shallow water (70 m), moderate environmental load



Location A parameters	Parked	Operating
Hub wind speed (m/s)	37	10.59 (rated)
Peak wave height (m)	13.95	7.20
Wave period (s)	11	11
Current (m/s)	$0.015 U_{hub}$	$0.015 U_{hub}$



Scenario A design space in parked load case

## Results (2/5) – Scenario A single-objective optimisation

- Single-objective: to find the design which **minimises the max. fairlead tension**, within constraints
- Optimisation problem was solved with 2 different methods: 1. simple **gradient-based method**, 2. **genetic algorithm** (both provided similar results)

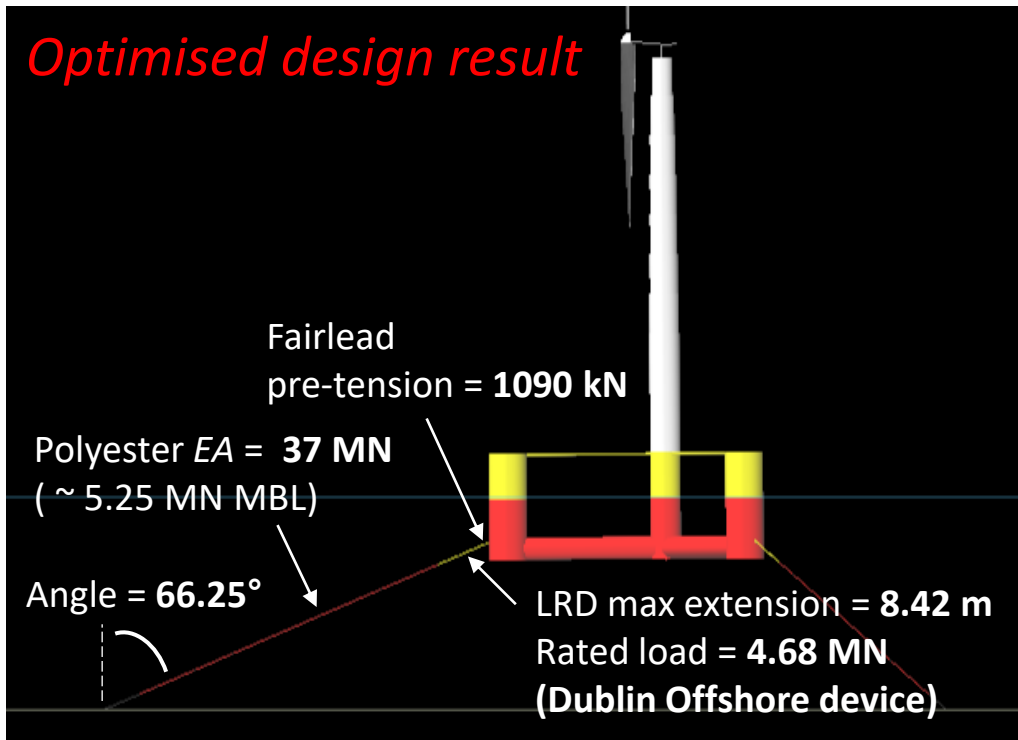
### Performance of optimised design:

	Motion	Output/ Constraint	Constraint utilisation
operating	Surge (m)	7.47/7.5	99.6 %
	Pitch (deg)	4.92/5	98.4 %
	Nacelle Acc. (g)	0.07/0.18	38.9 %
parked	Surge (m)	12.40/15	82.7 %
	Pitch (deg)	1.50/7	21.4 %
	Nacelle Acc. (g)	0.1/0.3	33.3 %

Maximum fairlead tension = **3.35 MN**



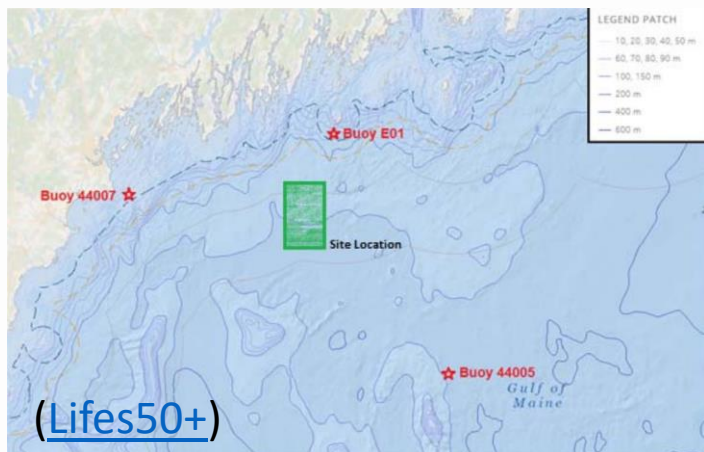
**51 % tension reduction** and **71 % footprint reduction** vs. 'conventional' catenary mooring



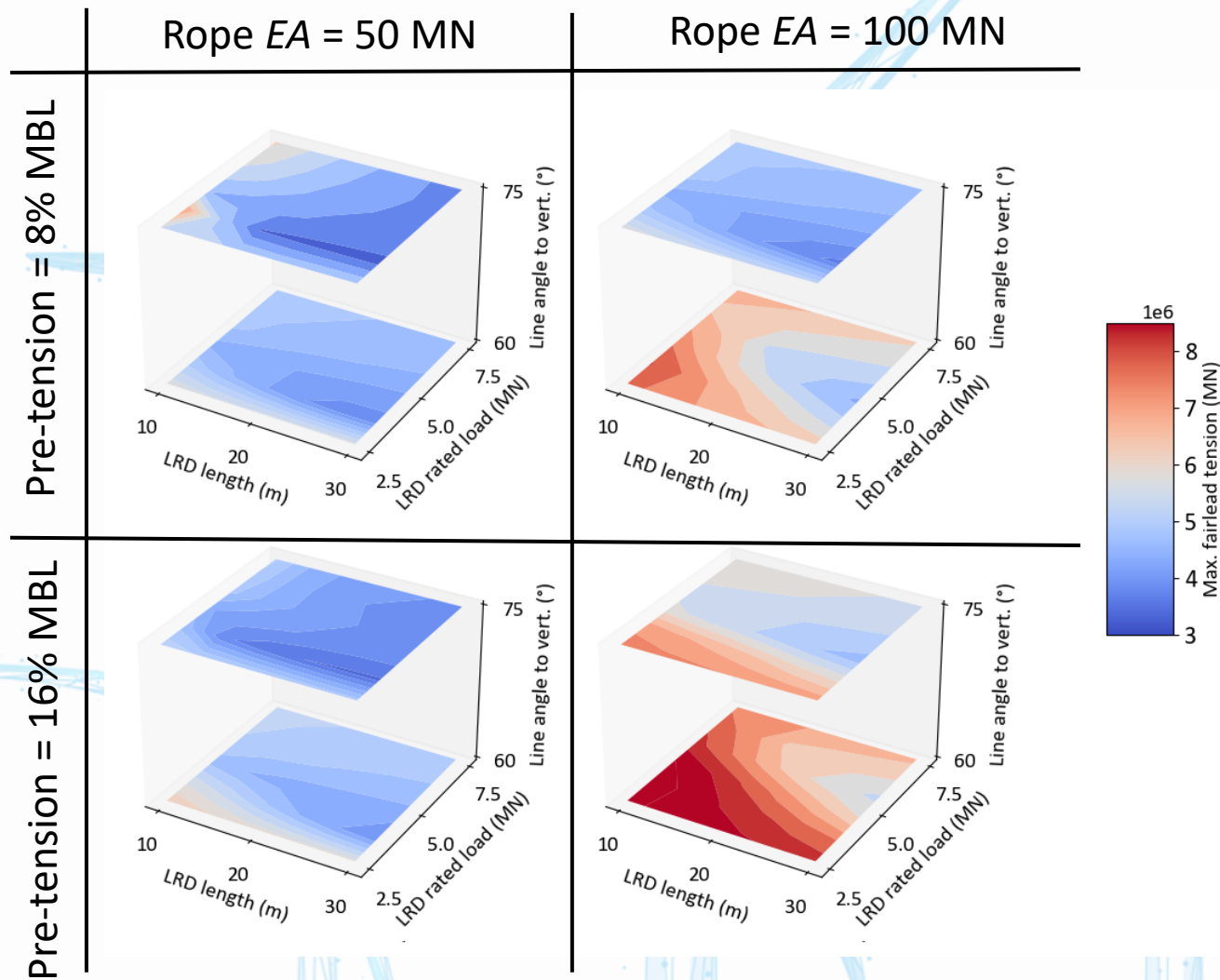


### Location B: Gulf of Maine

Intermediate depth (130 m), high environmental load



Location B parameters	Parked	Operating
Hub wind speed (m/s)	44	10.59 (rated)
Peak wave height (m)	20	13.8
Wave period (s)	16	13
Current (m/s)	$0.015 U_{hub}$	$0.015 U_{hub}$



Scenario B design space for parked load case

## Results (4/5) – Scenario B single-objective optimisation

### Performance of optimised design:

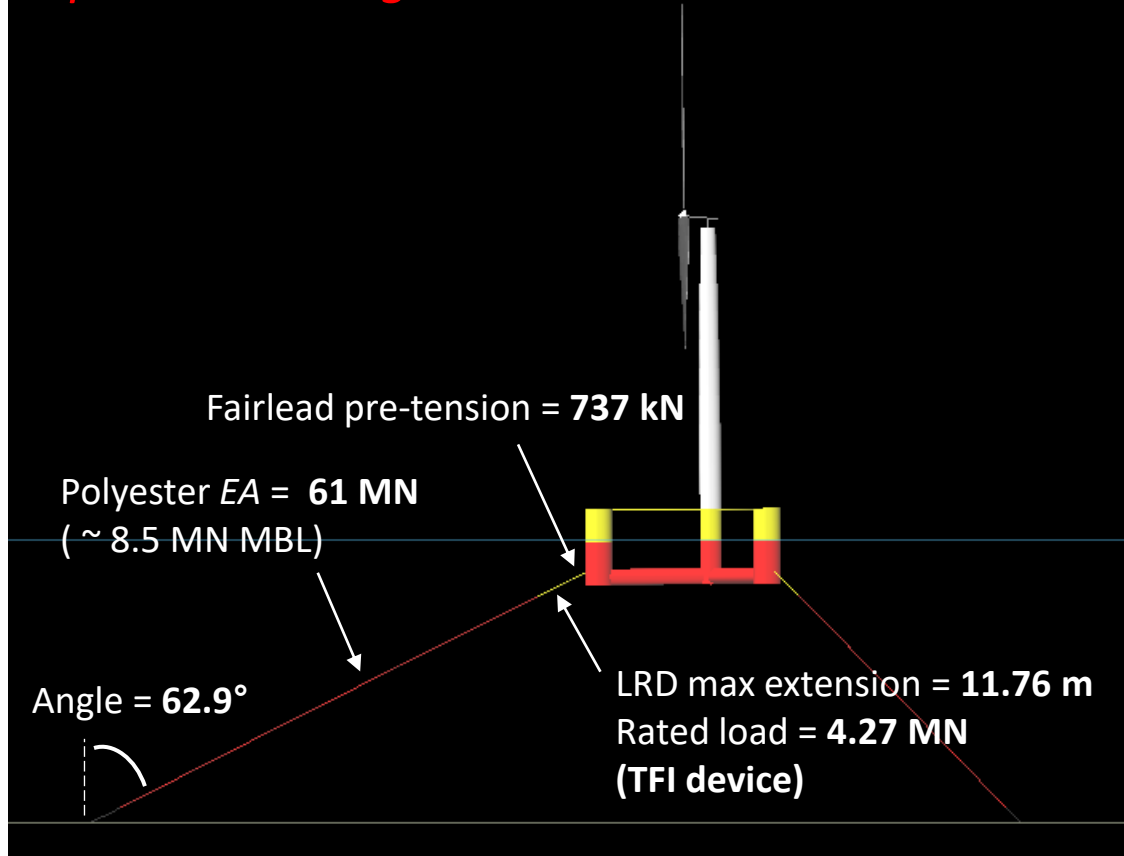
	Motion	Output/ Constraint	Constraint utilisation
operating	Surge (m)	13.27/15	88.5%
	Pitch (deg)	4.44/5	88.8%
	Nacelle Acc. (g)	0.14/0.18	77.8%
parked	Surge (m)	20.05/30	66.8%
	Pitch (deg)	2.76/7	39.4%
	Nacelle Acc. (g)	0.22/0.3	73.3%

Maximum fairlead tension = **4.02 MN**



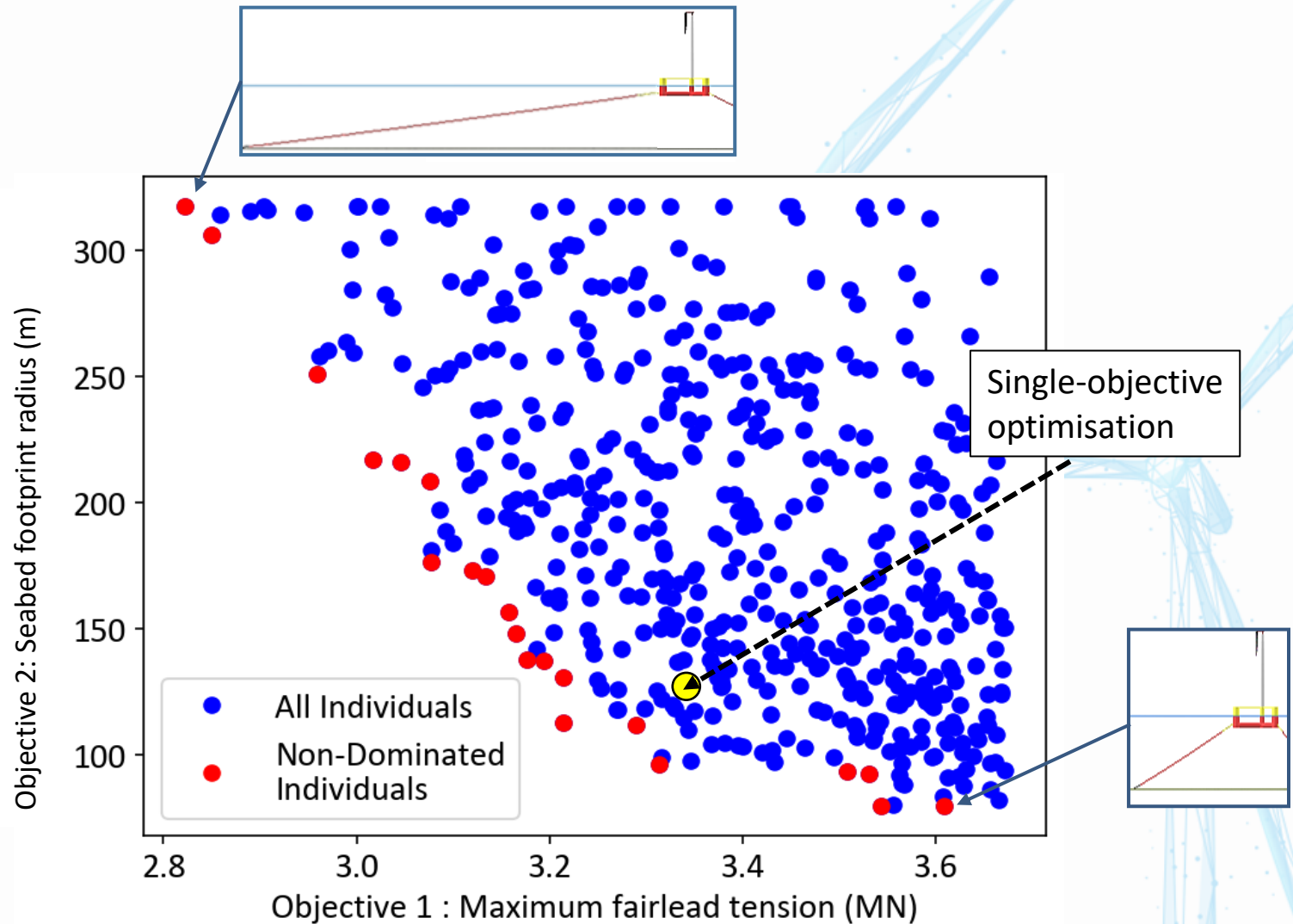
**61 % tension reduction and 63 % footprint reduction vs. 'conventional' catenary mooring**

### Optimised design result

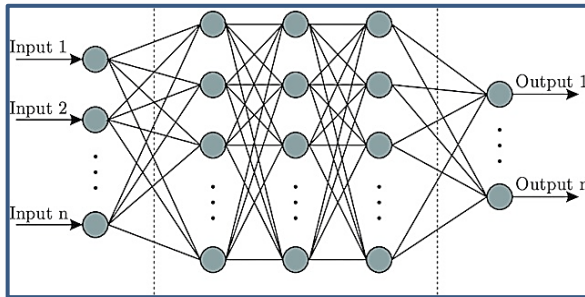
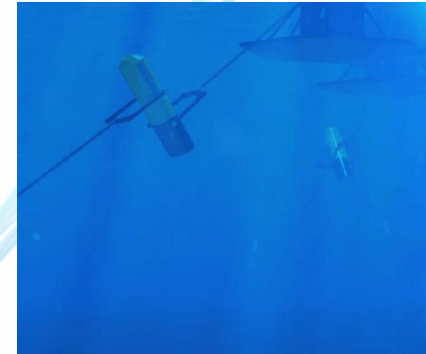


## Results (5/5) – Multi-objective optimisation

- A **genetic algorithm** can be used to find combinations of design parameters (i.e. ‘individuals’) which optimise *multiple objectives* simultaneously
- Any of the non-dominated individuals represent an **optimal compliant mooring system**
- This can provide **more useful results** than a single-objective optimisation



Combining **load reduction devices** with taut mooring systems can provide significant **tension reduction** and seabed **footprint reduction**



Using a **neural network-based surrogate model** allows the usage of various optimisation procedures, without running iterative dynamic analyses

This enables us to **reverse the design question**: using typical outputs of dynamic analyses (tension, platform motions etc.) as inputs to the optimisation procedure.



*Any questions?*

Feel free to get in touch by email: [o.g.festa@southampton.ac.uk](mailto:o.g.festa@southampton.ac.uk)