

JOOMMF Interactive Micromagnetic Simulations in Jupyter

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Introducing JOOMMF

- provides a user-friendly interface to the finite difference code **OOMMF** (<http://math.nist.gov/oommf/>)
- enables the use of **Jupyter notebooks** (jupyter.org), which can be run in any web browser (illustrated in Fig. 1)
- commands allow to run a full simulation workflow within a single notebook instead of using different tools in each step of the workflow (see Fig. 2)
- interaction of the frontend layer written in **Python 3** with OOMMF through `.mif`-configuration files¹
- extendable to other code packages in the future
- freely available on github (<https://github.com/joommf>)
- website with documentation: joommf.github.io

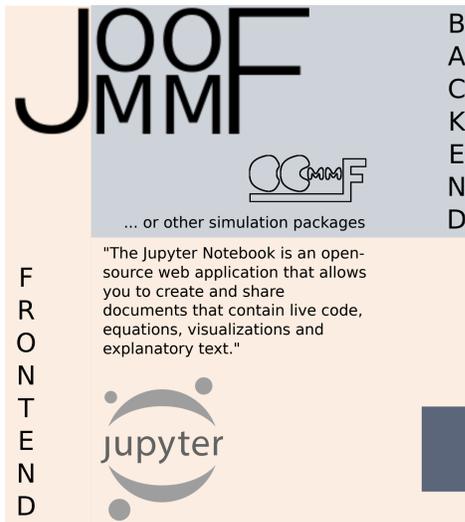


Fig. 1: JOOMMF = Jupyter + OOMMF

Single domain limit of a cubic magnetic particle²

Micromagnetic standard problem 3
 Authors: Marijan Beg, Ryan A. Pepper, and Hans Fangohr
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Problem specification
 This problem is to calculate a single domain limit of a cubic magnetic particle. This is the size L of equal energy for the so-called flower state (which one may also call a splayed state or a modified single-domain state) on the one hand, and the vortex or curling state on the other hand.

Geometry:
 A cube with edge length, L , expressed in units of the intrinsic length scale, $l_{ex} = \sqrt{A/K_m}$, where K_m is a magnetostatic energy density, $K_m = \frac{1}{2}\mu_0 M_s^2$.

Material parameters:

- uniaxial anisotropy K_u with $K_u = 0.1K_m$, and with the easy axis directed parallel to a principal axis of the cube $(0, 0, 1)$.
- exchange energy constant is $A = \frac{1}{2}\mu_0 M_s^2 l_{ex}^2$.

More details about the standard problem 3 can be found in Ref. 1.

Simulation
 Firstly, we import all necessary modules.

```
In [3]: import discretisedfield as df
import oommfc as oc
```

The following two functions are used for initialising the system's magnetisation [1].

```
In [4]: import numpy as np

# Function for initialising the flower state.
def m_init_flower(pos):
    X, Y, Z = pos[0]/1e-9, pos[1]/1e-9, pos[2]/1e-9
    mx = 0
    my = 2*z - 1
    mz = -2*y + 1
    norm_squared = mx**2 + my**2 + mz**2
    if norm_squared <= 0.05:
        return (1, 0, 0)
    else:
        return (mx, my, mz)

# Function for initialising the vortex state.
def m_init_vortex(pos):
    X, Y, Z = pos[0]/1e-9, pos[1]/1e-9, pos[2]/1e-9
    mx = 0
    my = np.sin(np.pi/2 * (x-0.5))
    mz = np.cos(np.pi/2 * (x-0.5))
    return (mx, my, mz)
```

Python functions to initialize the flower and the vortex state

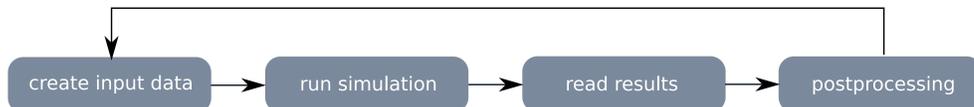


Fig. 2: Simulation workflow

```
In [3]: def minimise_system_energy(L, m_init):
    N = 16 # discretisation in one dimension
    cubysize = 100e-9 # cube edge length (m)
    cellsize = cubysize/N # discretisation in all three dimensions.
    lex = cubysize/L # exchange length.

    Km = 1e6 # magnetostatic energy density (J/m**3)
    Ms = np.sqrt(2*Km/oc.mu0) # magnetisation saturation (A/m)
    A = 0.5 * oc.mu0 * Ms**2 * lex**2 # exchange energy constant
    K = 0.1*Km # Uniaxial anisotropy constant
    u = (0, 0, 1) # Uniaxial anisotropy easy-axis

    p1 = (0, 0, 0) # Minimum sample coordinate.
    p2 = (cubysize, cubysize, cubysize) # Maximum sample coordinate.
    cell = (cellsize, cellsize, cellsize) # Discretisation.
    mesh = oc.Mesh(p1=(0, 0, 0), p2=(cubysize, cubysize, cubysize),
                  cell=(cellsize, cellsize, cellsize)) # Create a mesh object.

    system = oc.System(name="stdprob3")
    system.hamiltonian = oc.Exchange(A) + oc.UniaxialAnisotropy(K, u) + oc.Demag()
    system.m = df.Field(mesh, value=m_init, norm=Ms)

    md = oc.MinDriver()
    md.drive(system)

    return system
```

function, that returns the relaxed system object, argument L is the cube length in units of l_{ex}

the "system" object contains a set of properties, such as "hamiltonian" and "m"

here, the OOMMF configuration file (*.mif) is created for the energy minimization

energy minimization is executed starting from the vortex state

energy minimization is executed starting from the flower state

Energy crossing
 Now, we can plot the energies of both vortex and flower states as a function of cube edge length. This will give us an idea where the state transition occurs.

```
In [6]: L_array = np.linspace(8, 9, 11) # values of L for which the system is relaxed.

vortex_energies = []
flower_energies = []

for L in L_array:
    vortex = minimise_system_energy(L, m_init_vortex)
    flower = minimise_system_energy(L, m_init_flower)
    vortex_energies.append(vortex.total_energy())
    flower_energies.append(flower.total_energy())

# Plot the energy dependences.
import matplotlib.pyplot as plt
plt.plot(L_array, vortex_energies, 'o-', label='vortex')
plt.plot(L_array, flower_energies, 'o-', label='flower')
plt.xlabel('L (lex)')
plt.ylabel('E')
plt.xlim([8.0, 9.0])
plt.grid()
plt.legend()
```

for-loop to step through the values for the cube length L and compute the corresponding energies

We now know that the energy crossing occurs between $8L_{ex}$ and $9L_{ex}$, so a bisection algorithm can be used to find the exact crossing.

```
In [7]: from scipy.optimize import bisect

def energy_difference(L):
    vortex = minimise_system_energy(L, m_init_vortex)
    flower = minimise_system_energy(L, m_init_flower)
    return vortex.total_energy() - flower.total_energy()

cross_section = bisect(energy_difference, 8, 9, xtol=0.1)

print("The transition between vortex and flower states occurs at {}*lex".format(cross_section))
The transition between vortex and flower states occurs at 8.4375*lex
```

Python's "scipy"-module provides a wide range of useful algorithms for further data evaluation

References
 [1] μ MAG Site Directory <http://www.ctcms.nist.gov/~rdm/mumag.org.html>

¹ Beg, M., Pepper R., Fangohr H., AIP Advances 7, 056025 (2017)

² mumag Standard Problem #3: <http://www.ctcms.nist.gov/~rdm/mumag.org.html>